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In Project>Configure>C compiler do not forget to set following options : Chip : ATmega16 (or whatever you are using) Clock : 16MHz (or whatever you are using) Experiment with these programs and try to learn more from it. Blink LED on PB0 at a rate of 1Hz.

ATMEL AVR Tutorial 2 - Embedded Electronics Blog

Types of Interrupts There are two types of interrupts: Hardware Interrupt: It happens when an external event occurs like an external interrupt pin changes its state from LOW to HIGH or HIGH to LOW. Software Interrupt: It happens according to the instruction from the software.For example Timer interrupts are software interrupt.. Interrupts in Arduino

Arduino Interrupts Tutorial with Example Interrupt ...

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The complete circuit diagram for arduino line follower robot is shown in the above image. As you can see the output of comparators is directly connected to Arduino digital pin number 2 and 3. And motor driver's input pin 2, 7, 10 and 15 is connected to Arduino's digital pin number 4, 5, 6 and 7 respectively.

Arduino Line Follower Robot Code and Circuit Diagram

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